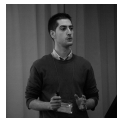


The Imprecise Kolmogorov Model for robustifying p -boxes

David Nieto-Barba, Ignacio Montes, Enrique Miranda



University of Oviedo



SMPS 2026, Lecce

- We consider a distortion procedure for lower probabilities that transforms p -boxes into p -boxes.
- Our model is based on the Kolmogorov distance between cumulative distribution functions.
- We investigate the main properties of the model as a distortion procedure.

Let $\mathcal{X} = \{x_1, \dots, x_n\}$ be a *totally ordered* finite possibility space: $x_i \preceq x_j \iff i \leq j$.

We denote by $\mathbb{P}(\mathcal{X})$ the set of probability measures on $\mathcal{P}(\mathcal{X})$ and by

$$\mathcal{L}(\mathcal{X}) := \{f : \mathcal{X} \rightarrow \mathbb{R}\}$$

the set of **gambles** on $\mathcal{X}$.

Lower probabilities and previsions

A **lower probability** a monotone increasing function $\underline{P} : \mathcal{P}(\mathcal{X}) \rightarrow [0, 1]$ s.t. $\underline{P}(\emptyset) = 0, \underline{P}(\mathcal{X}) = 1$. Its conjugate **upper probability** $\bar{P}$ is given by $\bar{P}(A) = 1 - \underline{P}(A^c)$.

The associated **credal set** $\mathcal{M}(\underline{P})$ is given by

$$\mathcal{M}(\underline{P}) := \{P \in \mathbb{P}(\mathcal{X}) \mid \bar{P}(A) \geq P(A) \geq \underline{P}(A) \quad \forall A \subseteq \mathcal{X}\}.$$

Similarly, a **lower prevision** is a function $\underline{P} : \mathcal{L}(\mathcal{X}) \rightarrow \mathbb{R}$, and its conjugate **upper prevision** $\bar{P}$ is given by $\bar{P}(f) = -\underline{P}(-f)$.

The associated **credal set** $\mathcal{M}(\underline{P})$ is given by

$$\mathcal{M}(\underline{P}) := \{P \in \mathbb{P}(\mathcal{X}) \mid \bar{P}(f) \geq P(f) \geq \underline{P}(f) \quad \forall f \in \mathcal{L}(\mathcal{X})\}.$$

Avoiding sure loss and coherence

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

A lower prevision (resp., probability) $\underline{P}$ **avoids sure loss** when $\mathcal{M}(\underline{P})$ is non-empty, and it is **coherent** when it can be recovered as the lower envelope of $\mathcal{M}(\underline{P})$:

$$\underline{P}(f) = \min\{P(f) : P \in \mathcal{M}(\underline{P})\} \quad \forall f \in \mathcal{L}(\mathcal{X})$$

or

$$\underline{P}(A) = \min\{P(A) : P \in \mathcal{M}(\underline{P})\} \quad \forall A \subseteq \mathcal{X}.$$

Coherence will be the minimal rationality requirement in this work.

As particular cases of coherent lower probabilities, we have:

- ▶ **2-monotone capacities:** $\underline{P}(A \cup B) + \underline{P}(A \cap B) \geq \underline{P}(A) + \underline{P}(B) \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ **Belief functions:** $\underline{P}(\cup_{i=1}^k A_i) \geq \sum_{\emptyset \neq I \subseteq \{1, \dots, k\}} (-1)^{|I|+1} \underline{P}(\cap_{i \in I} A_i)$
 $\forall A_1, \dots, A_k \subseteq \mathcal{X}, \quad \forall k \in \mathbb{N}.$
- ▶ **Minitive measures:** $\underline{P}(A \cap B) = \min\{\underline{P}(A), \underline{P}(B)\} \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ **p -boxes.**

As particular cases of coherent lower probabilities, we have:

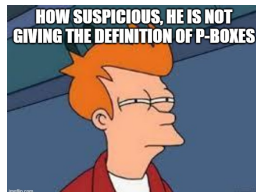
- ▶ **2-monotone capacities:** $\underline{P}(A \cup B) + \underline{P}(A \cap B) \geq \underline{P}(A) + \underline{P}(B) \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ **Belief functions:** $\underline{P}(\cup_{i=1}^k A_i) \geq \sum_{\emptyset \neq I \subseteq \{1, \dots, k\}} (-1)^{|I|+1} \underline{P}(\cap_{i \in I} A_i)$
 $\forall A_1, \dots, A_k \subseteq \mathcal{X}, \quad \forall k \in \mathbb{N}.$
- ▶ **Minitive measures:** $\underline{P}(A \cap B) = \min\{\underline{P}(A), \underline{P}(B)\} \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ **p -boxes.**

$\hookrightarrow$ The more general model of coherent lower previsions allow in particular to encompass **comparative probabilities** and other types of credal sets.

Particular cases

As particular cases of coherent lower probabilities, we have:

- ▶ **2-monotone capacities:** $\underline{P}(A \cup B) + \underline{P}(A \cap B) \geq \underline{P}(A) + \underline{P}(B) \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ **Belief functions:** $\underline{P}(\cup_{i=1}^k A_i) \geq \sum_{\emptyset \neq I \subseteq \{1, \dots, k\}} (-1)^{|I|+1} \underline{P}(\cap_{i \in I} A_i)$
 $\forall A_1, \dots, A_k \subseteq \mathcal{X}, \quad \forall k \in \mathbb{N}.$
- ▶ **Minitive measures:** $\underline{P}(A \cap B) = \min\{\underline{P}(A), \underline{P}(B)\} \quad \forall A, B \subseteq \mathcal{X}.$
- ▶ ***p*-boxes.**



So what is a p -box?

A p -box is a couple $(\underline{F}, \overline{F})$ of cumulative distribution functions $\underline{F}, \overline{F} : \mathcal{X} \rightarrow [0, 1]$ that are monotone with respect to the total order $\preceq$.

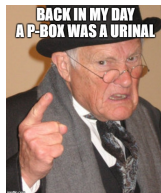
Its associated **credal set** is

$$\mathcal{M}(\underline{F}, \overline{F}) := \{P \in \mathbb{P}(\mathcal{X}) \mid \underline{F}(x) \leq F_P(x) \leq \overline{F}(x) \quad \forall x \in \mathcal{X}\},$$

where F_P is the CDF associated with P , and $\mathcal{M}(\underline{F}, \overline{F}) \neq \emptyset$ if and only if $\underline{F} \leq \overline{F}$.

The lower envelopes of $\mathcal{M}(\underline{F}, \overline{F})$ determine coherent lower probabilities and previsions.

↪ In particular, the associated coherent lower probabilities are belief functions!



From lower probabilities to p -boxes

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

A lower and an upper probability determine a p -box by

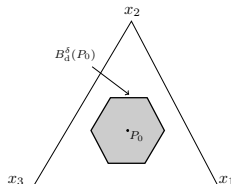
$$\underline{F}_{\underline{P}}(x_i) := \underline{P}(\{x_1, \dots, x_i\}) \text{ and } \overline{F}_{\overline{P}}(x_i) := \overline{P}(\{x_1, \dots, x_i\}) \quad \forall i \in \{1, \dots, n\}.$$

However, in general it holds that $\mathcal{M}(\underline{P}) \subseteq \mathcal{M}(\underline{F}_{\underline{P}}, \overline{F}_{\overline{P}})$, with equality if and only if $\underline{P}$ is determined by a p -box $(\underline{F}, \overline{F})$.

Distortion models

One natural procedure to obtain a coherent lower probability is to consider a **distortion model**: we consider a neighbourhood around a probability measure P_0 determined some distortion function d and by a given radius δ , which may represent:

- the proportion of contaminated data;
- the fee taken by the betting house;
- the distance to the original model we want to be robust;
- ...



Example: the Kolmogorov model

Given $Q, P \in \mathbb{P}(\mathcal{X})$, their **Kolmogorov distance** is

$$d_{\text{KM}}(Q, P) := \max_{x \in \mathcal{X}} |F_P(x) - F_Q(x)|.$$

d_{KM} determines the neighbourhood

$$B_{\text{KM}}^{\delta}(P) = \{Q \in \mathbb{P}(\mathcal{X}) \mid F_P(x) - \delta \leq F_Q(x) \leq F_P(x) + \delta \quad \forall x \in \mathcal{X}\}.$$

which coincides with the credal set of a coherent p -box with CDFs

$$\underline{F}(x) := \max\{F_P(x) - \delta, 0\} \quad \text{and} \quad \overline{F}(x) := \min\{F_P(x) + \delta, 1\},$$

for every $x \in \mathcal{X} \setminus \{x_n\}$ and $\underline{F}(x_n) = \overline{F}(x_n) := 1$, meaning that $\mathcal{M}(\underline{F}, \overline{F}) = B_{\text{KM}}^{\delta}(P)$.

So, are we done?

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

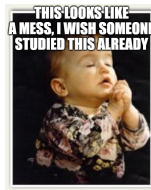
Introduction

The IKM

Conclusions

In some cases we may be interested in distorting a model that is already imprecise:

- To transform a lower probability that does not avoid sure loss into one that does;
- To obtain a model with better properties, while keeping the available information;
- To reduce the number of extreme points of the credal set;
- In a consensus seeking process;
- ...



Distortions of lower probabilities

Let $\Lambda = [0, \infty)$ and $\{\phi_\delta : [0, 1] \rightarrow [0, 1]\}_{\delta \in \Lambda}$ be a family of non-decreasing functions such that $\phi_\delta(t) \leq t$ for each $t \in [0, 1]$ and $\delta \in \Lambda$.

Given a lower probability $\underline{P}$ and $\delta \in \Lambda$, its **distorted lower probability** with **distorting factor** δ is defined as

$$\underline{Q}_\delta[\underline{P}](A) := (\phi_\delta \circ \underline{P})(A) = \phi_\delta(\underline{P}(A))$$

for every $A \subset \mathcal{X}$ and $\underline{Q}_\delta[\underline{P}](\mathcal{X}) := 1$.

Example: the Imprecise Total Variation

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

Let $\underline{P}$ be a coherent lower probability and $\delta > 0$. The **imprecise total variation model** induced by $(\underline{P}, \delta)$ is the lower probability $\underline{Q}_\delta$ given by

$$\underline{Q}_\delta(A) = \max \{ \underline{P}(A) - \delta, 0 \} \quad \forall A \subset \mathcal{X}, \quad \underline{Q}_\delta(\mathcal{X}) = 1.$$



Desirable properties

The Imprecise
Kolmogorov
Model for
robustifying
 ρ -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

(P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.

Desirable properties

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

(P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.

(P2) (Semigroup) (a) $\underline{Q}_0[\underline{P}] = \underline{P}$; and (b) $\underline{Q}_{\delta_2+\delta_1}[\underline{P}] = \underline{Q}_{\delta_2}[\underline{Q}_{\delta_1}[\underline{P}]]$ for any $\delta_1, \delta_2 \in \Lambda$.

Desirable properties

- (P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.
- (P2) (Semigroup) (a) $\underline{Q}_0[\underline{P}] = \underline{P}$; and (b) $\underline{Q}_{\delta_2+\delta_1}[\underline{P}] = \underline{Q}_{\delta_2}[\underline{Q}_{\delta_1}[\underline{P}]]$ for any $\delta_1, \delta_2 \in \Lambda$.
- (P3) (Structure preservation) If $\underline{P}$ belongs to a subfamily $\mathcal{H}$ of lower probabilities, then so does $\underline{Q}_{\delta}[\underline{P}]$ for every $\delta \in \Lambda$.

Desirable properties

- (P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.
- (P2) (Semigroup) (a) $\underline{Q}_0[\underline{P}] = \underline{P}$; and (b) $\underline{Q}_{\delta_2+\delta_1}[\underline{P}] = \underline{Q}_{\delta_2}[\underline{Q}_{\delta_1}[\underline{P}]]$ for any $\delta_1, \delta_2 \in \Lambda$.
- (P3) (Structure preservation) If $\underline{P}$ belongs to a subfamily $\mathcal{H}$ of lower probabilities, then so does $\underline{Q}_{\delta}[\underline{P}]$ for every $\delta \in \Lambda$.
- (P4) (Reversibility) Given $\delta \in \Lambda$ and $\underline{P}$, there exists ϕ_{δ}^{-1} such that $\underline{P} = \phi_{\delta}^{-1} \circ \underline{Q}_{\delta}[\underline{P}]$.

Desirable properties

- (P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.
- (P2) (Semigroup) (a) $\underline{Q}_0[\underline{P}] = \underline{P}$; and (b) $\underline{Q}_{\delta_2+\delta_1}[\underline{P}] = \underline{Q}_{\delta_2}[\underline{Q}_{\delta_1}[\underline{P}]]$ for any $\delta_1, \delta_2 \in \Lambda$.
- (P3) (Structure preservation) If $\underline{P}$ belongs to a subfamily $\mathcal{H}$ of lower probabilities, then so does $\underline{Q}_{\delta}[\underline{P}]$ for every $\delta \in \Lambda$.
- (P4) (Reversibility) Given $\delta \in \Lambda$ and $\underline{P}$, there exists ϕ_{δ}^{-1} such that $\underline{P} = \phi_{\delta}^{-1} \circ \underline{Q}_{\delta}[\underline{P}]$.
- (P5) (Expression as an imprecise neighbourhood model) There exists a *distorting function* $d : \mathbb{P}(\mathcal{X}) \times \mathbb{P}(\mathcal{X}) \rightarrow [0, \infty)$ such that, given $\underline{P}$, for every $\delta \in \Lambda$ and $Q \in \mathbb{P}(\mathcal{X})$

$$\mathcal{M}(\underline{Q}_{\delta}[\underline{P}]) = \{Q \in \mathbb{P}(\mathcal{X}) \mid d(Q, \underline{P}) \leq \delta\} =: B_d^{\delta}(\underline{P}).$$

Desirable properties

- (P1) (Expansion) For any $\underline{P}$ and $\delta_1, \delta_2 \in \Lambda$, $\delta_1 \geq \delta_2$ implies $\underline{Q}_{\delta_1}[\underline{P}] \leq \underline{Q}_{\delta_2}[\underline{P}]$.
- (P2) (Semigroup) (a) $\underline{Q}_0[\underline{P}] = \underline{P}$; and (b) $\underline{Q}_{\delta_2 + \delta_1}[\underline{P}] = \underline{Q}_{\delta_2}[\underline{Q}_{\delta_1}[\underline{P}]]$ for any $\delta_1, \delta_2 \in \Lambda$.
- (P3) (Structure preservation) If $\underline{P}$ belongs to a subfamily $\mathcal{H}$ of lower probabilities, then so does $\underline{Q}_{\delta}[\underline{P}]$ for every $\delta \in \Lambda$.
- (P4) (Reversibility) Given $\delta \in \Lambda$ and $\underline{P}$, there exists ϕ_{δ}^{-1} such that $\underline{P} = \phi_{\delta}^{-1} \circ \underline{Q}_{\delta}[\underline{P}]$.
- (P5) (Expression as an imprecise neighbourhood model) There exists a *distorting function* $d : \mathbb{P}(\mathcal{X}) \times \mathbb{P}(\mathcal{X}) \rightarrow [0, \infty)$ such that, given $\underline{P}$, for every $\delta \in \Lambda$ and $Q \in \mathbb{P}(\mathcal{X})$

$$\mathcal{M}(\underline{Q}_{\delta}[\underline{P}]) = \{Q \in \mathbb{P}(\mathcal{X}) \mid d(Q, \underline{P}) \leq \delta\} =: B_d^{\delta}(\underline{P}).$$

- (P6) (Strong commutativity) If $\underline{P}$ is coherent, then for every $\delta \in \Lambda$ it holds:

$$\mathcal{M}(\underline{Q}_{\delta}[\underline{P}]) = \bigcup_{P \in \mathcal{M}(\underline{P})} \mathcal{M}(\underline{Q}_{\delta}[P]).$$

The Imprecise Kolmogorov model

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

Given $\delta \in [0, +\infty)$, the **Imprecise Kolmogorov Model** (IKM) $(\underline{G}_\delta[\cdot], \overline{G}_\delta[\cdot])$ is given by :

$$\underline{G}_\delta[\underline{F}](x) := \max \{ \underline{F}(x) - \delta, 0 \} \quad \text{and} \quad \overline{G}_\delta[\overline{F}](x) := \min \{ \overline{F}(x) + \delta, 1 \},$$

for each $x \in \mathcal{X} \setminus \{x_n\}$, with $\underline{G}_\delta[\underline{F}](x_n) = \overline{G}_\delta[\overline{F}](x_n) := 1$.

The Imprecise Kolmogorov model

Given $\delta \in [0, +\infty)$, the **Imprecise Kolmogorov Model** (IKM) $(\underline{G}_\delta[\cdot], \overline{G}_\delta[\cdot])$ is given by :

$$\underline{G}_\delta[\underline{F}](x) := \max \{ \underline{F}(x) - \delta, 0 \} \quad \text{and} \quad \overline{G}_\delta[\overline{F}](x) := \min \{ \overline{F}(x) + \delta, 1 \},$$

for each $x \in \mathcal{X} \setminus \{x_n\}$, with $\underline{G}_\delta[\underline{F}](x_n) = \overline{G}_\delta[\overline{F}](x_n) := 1$.

- It follows by definition that this satisfies expansion (P1) and semigroup (P2). ✓



Structure preservation and reversibility

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

Concerning structure preservation (P3), the IKM always gives a p -box, which is in particular a belief function (hence 2-monotone and coherent).

Structure preservation and reversibility

Concerning structure preservation (P3), the IKM always gives a p -box, which is in particular a belief function (hence 2-monotone and coherent).

- If $(\underline{E}, \overline{F})$ is a minitive p -box, then $(\underline{G}_\delta[\underline{E}], \overline{G}_\delta[\overline{F}])$ is minitive iff either $\underline{E}(x) = 0$ for any $x \neq x_n$ or $\overline{F}(x) = 1$ for any $x \in \mathcal{X}$.



Structure preservation and reversibility

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

Concerning structure preservation (P3), the IKM always gives a p -box, which is in particular a belief function (hence 2-monotone and coherent).

- If $(\underline{F}, \overline{F})$ is a minitive p -box, then $(\underline{G}_\delta[\underline{F}], \overline{G}_\delta[\overline{F}])$ is minitive iff either $\underline{F}(x) = 0$ for any $x \neq x_n$ or $\overline{F}(x) = 1$ for any $x \in \mathcal{X}$.

With respect to reversibility (P4), given a p -box $(\underline{F}, \overline{F})$ and $\delta \geq 0$, the IKM satisfies (P4) iff $\delta < \min \{ \underline{F}(x_1), 1 - \overline{F}(x_{n-1}) \}$.

Expression as a neighbourhood model

Consider $d_{\text{IKM}} : \mathbb{P}(\mathcal{X}) \times \mathbb{F}(\mathcal{X}) \times \mathbb{F}(\mathcal{X}) \rightarrow [0, +\infty)$ given by:

$$d_{\text{IKM}}(Q, \underline{F}, \overline{F}) := \max_{x \in \mathcal{X}} \left\{ \max \{ \underline{F}(x) - F_Q(x), F_Q(x) - \overline{F}(x) \} \right\},$$

for every $Q \in \mathbb{P}(\mathcal{X})$ and $\underline{F}, \overline{F} \in \mathbb{F}(\mathcal{X})$.

► d_{IKM} generalises the Kolmogorov distance.

$$(P5) \quad B_{d_{\text{IKM}}}^{\delta}(\underline{F}, \overline{F}) = \mathcal{M}(\underline{G}_{\delta}[\underline{F}], \overline{G}_{\delta}[\overline{F}]). \quad \checkmark$$

Strong Commutativity

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions

Let $(\underline{E}, \overline{F})$ be a coherent p -box with associated lower probability $\underline{P}_{(\underline{E}, \overline{F})}$.

$$d_{\text{IKM}}(Q, \underline{P}_{(\underline{E}, \overline{F})}) = \min_{P \in \mathcal{M}(\underline{P}_{(\underline{E}, \overline{F})})} d_{\text{KM}}(Q, P) \quad \forall Q \in \mathbb{P}(\mathcal{X}).$$

$\hookrightarrow$ Thus, IKMs satisfy strong commutativity (P6). ✓

Conclusions and future work

- ▶ IKMs satisfy the main properties of interest for an imprecise distortion model.
- ▶ While applicable to arbitrary lower probabilities, they only take into account the associated p -box.
- ▶ They also differ from the outcome of the Imprecise Total Variation Model.

- ▶ IKMs satisfy the main properties of interest for an imprecise distortion model.
- ▶ While applicable to arbitrary lower probabilities, they only take into account the associated p -box.
- ▶ They also differ from the outcome of the Imprecise Total Variation Model.

Future work:



Other possible distortions of p -boxes.



Connections with game theory.

Some references



S. Moral. *Discounting Imprecise Probabilities*. In: The Mathematics of the Uncertain, 685-697. Springer, 2018.



D. Nieto-Barba, I. Montes, E. Miranda. *The Imprecise Total Variation Model and its connections with game theory*. Fuzzy Sets and Systems, 517, 109448, 2025.



D. Nieto-Barba, E. Miranda, and I. Montes. *Distortions of lower probabilities as a tool for avoiding conflict*. Proceedings of ECSQARU 2025, pages 133–147.



M.C.M. Troffaes, E. Miranda, S. Destercke. *On the connection between probability boxes and possibility measures*. Information Sciences 224, 88–108, 2013.



Project **PID2022-140585NB-I00** funded by MICIU/AEI/10.13039/501100011033 y por FEDER, UE

Thank you (again) for the attention...

...and for the questions!

The Imprecise
Kolmogorov
Model for
robustifying
 p -boxes

Nieto-Barba,
Montes, Miranda

Introduction

The IKM

Conclusions